1. Notice

It is used in industry sewing machine. For perfect operation and safety, installation and operation must be supervised by professional.

1.1 Work Environment

▲ Please use 220VAC in ±10% ranges.

▲ To avoid the false operation please keep the product away from the high electromagnetic interference.

▲ Please operate in the area which temperature is 5° C~45°C and humidity is 80% or less.

▲ Please keep the product away from the flammability and exploder.

1.2 Notice of Installation

▲ Turn off the power and unplug the cord before installation.

▲The wire must not set to be near the wheel and other movable parts.

▲ To avoid the static interference and current leakage, all grounding must be done.

1.3 Notice of Safety

▲ Turn off the power before maintenance and repairs or raising the machine arm, or changing needle, or threading needle.

▲ Please don't open the box except the professional.

▲ When turn on the machine in the first time, use low speed to operate and check the correct rotation direction.

▲ During machine operation, don't touch any moving parts.

▲ All moving parts must use the protective device to avoid the body contact and objects insertion.

▲When there is water or other liquid, or caustic material on box or motor, you must stop operation and turn off the power.

▲ All connector shouldn't be plug and unplug when power on.

▲The connector should be plug and unplug in the correct method.

2. Power Connection

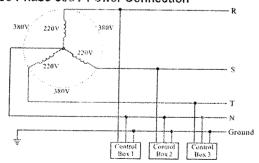
2.1 Single Phase 220V Power Connection

Ground wire (green & yellow) must be grounding

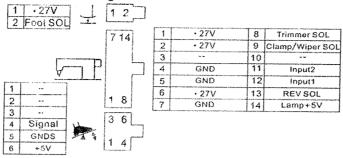
Brown wire AC 220V

Green / Yellow wire

2.2 Three Phase 380V Power Connection

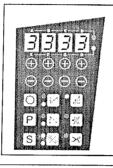


3. Connector Diagram



Note: Input1 default is RVS switch, Input2 default is COR switch.

4. Function of Operation Box



| SN. | Key | Operation | | | | |
|-----|----------|--|--|--|--|--|
| | | Start backtack: Top LED set single, bottom | | | | |
| 1 | · Tank | LED set double. The number of start | | | | |
| ' | • 2 | backtack stitches (1~15) in the A and B of | | | | |
| | | the display are sewn. | | | | |
| | | End backtack: Top LED set single, bottom | | | | |
| 2 | | LED set double. The number of end | | | | |
| _ | • | backtack stitches (1~15) in the C and D of | | | | |
| | | the display are sewn. | | | | |
| 3 | | Mode: Top LED set Continuous Backtack, | | | | |
| | | bottom LED set Fixed Stitch. | | | | |
| 4 | W.* | Clamp/wiper: See 5.7 | | | | |
| 5 | \$ (1/2) | Needle Up/Down: See 5.3 | | | | |
| 6 | * (*) | Thread trimming: See 5.5 | | | | |
| 7 | (P) | Enter or exit the interface of Parameter | | | | |
| 8 | (S) | Confirm operation or Save value | | | | |
| 9 | 0 | Switch "ABCD" or "EFGH" | | | | |
| 10 | 0 | Increase value | | | | |
| 11 | 0 | Decrease value | | | | |

5. Operation

5.1 Setup Parameter

5.1.1 Modify Value

Default Interface: Press P will be into select parameter interface.

Select Parameter Interface: Press A+/- to select type.

Generally, you can select S/T/A, if you press P for 1 second or more when power on, you can select S/T/A/D/O after display "O EN". Press C+/- and D+/- to select index. Press S will be into modifying value interface. Press P will be return Default Interface

Modifying Value Interface: Press to modify value or press to recall the default value. Press to confirm and save or press to repeal change, and return Select Parameter

Interface.

5.1.2 Parameter Solidifying

If you want to **change** parameter's **default value**: Select the parameter index, press of for 1 second or more, after "SD OK" displaying, the default value has been changed.

Reset to defaults: Set O17 to "1", then restart and display "INIT". Display "OK" after finished.

5.1.3 Reset to Factory Defaults

One way: Set O51 to "1", then restart and display "INIT". Display "OK" after finished.

Another way: Press for 1 second or more when power on, display "INIT". Display "OK" after finished.

5.1.4 Encrypt the Parameter Interface

First change **O27** to set password then set **O15** to "1". After this, accessing to parameter interface will be in password interface firstly, input the correct password and press S to confirm. **5.2** Set Sewing Mode

Press select LED side key: Top LED set Continuous Backtack, bottom LED set Fixed Stitch.

5.2.1 Sewing Continuous Backtack Stitches

Press select LED side display area: Top LED illuminates and the number of stitches (1~15) for A, B, C and D are displayed. Bottom LED illuminates and the number of segments (1~15) for A.

5.2.2 Sewing Fixed Stitches

Every segments can set own backtack, stitches and thread trimming.

Press select LED side display area: Top LED illuminates and the number of backtack stitches (1~15) for A, B, C and D are displayed. Bottom LED illuminates and the number of segments (1~35) for A, the number of stitches (1~99) of current segment for C and D. After one segment sewing finished, automatic display next segment.

Set the maximum segment: if you need N segments, please set the number of stitches of the segment N+1 to 0.

Set automatic sewing: Set A02 to 1, turn of the automatic sewing function, the Fixed Stitches are sewn simply by depressing the treadle once without needing to depress it continuously.

5.3 Set Needle Up/Down

Press select Needle Up/Down, when the LED is illuminated, the needle bar stops in the up position, otherwise the needle bar stops in the down position.

5.4 Set Slow Start

Set A21 to "1", the first N stitches sewing after the thread is trimmed are sewn at lower speed. Set O01 to "the first N stitches", Set S08 to "lower speed".

5.5 Set Thread Trimming

Press change LED side key: when the LED is illuminated, the thread is trimming automatically after sewn.

5.6 Set Foot Lifter

Set A09 to "1", enable foot lift.

Set A14 to "1", the foot lifter will lift automatically when stop. Set A15 to "1", the foot lifter will lift automatically after

trimming.

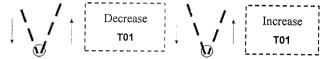
5.7 Set Clamp (or Wiper)

Press change LED side key: when the LED is illuminated, enable Clamp (or wiper).

5.8 Adjust the Backtack

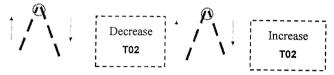
5.8.1 Adjusting of RVE. SOL. Action Time (T01)

For Start/End Backtack or Continuous Backtack, if unbalanced situation is appeared during reverse direction to natural direction, please correct it as below:



5.8.2 Adjusting of RVE. SOL. release time (T02)

For Start/End Backtack or Continuous Backtack, if unbalanced situation is appeared during reverse direction to natural direction, please correct it as below:



5.9 The Function of Input1/Input2 Button

Buttons are multi-function. A04 set input1, A05 set input2.

- 0 Reverse only
- 1 Positioning the needle up/down only
- 2 Correct stitches only
- 3 Positioning the needle up/down when stop, reverse when sewing
- 4 Correct stitches when stop, reverse when sewing
- 5 Correct stitches and reverse when stop, reverse when sewing
- 6 reserved
- 7 End Backtack and thread trimming before thread trimming, auto-lifter after thread trimming.
- 8 Auto-lifter: Up lift when press the button, down lift when press the button again.

5.10 Safety Switch

Set O31 to "1", if turn up the Machine head, can't sew and display "CARE".

5.11 Automatically Move to Up Position

Set A18 to "1", the machine will move to up position and stop automatically as power on.

5.12 Counting the Product Quantity

Set A11 to "1", press of for 1 second or more to turn off all LED side display area. The counter for A, B, C and D are displayed.

Press S for 1 second or more will be into collect process interface. A displays "L", B, C and D display the number of stitches of process. It record the number of stitches and the number of trimming times .Finished collect, press S for 1 second or more return Sewing Interface.

If sewn the number stitches more than the number of stitches

collected 90%, and the number of trimming times more than collected, the counter add 1.

Press "A-" for 1 second or more, clear counter.

5.13 The Lower Thread Counter

The lower thread counter can be used to let you know approximately how much lower thread is remaining.

Set A12 to "1" enable the counter. Press of for 1 second or more, illuminate all LED side display area, remain thread for A B C and D are displayed.

Press S for 1 second or more, the lower thread counter display will show the initial value which was set previously.

Press •/• , set the initial value (1~9999).

The counter reduces by 1 for every 10 stitches sewn. If the counter less than 1, the display area will warning and buzzer sounds for 3 times. After thread trimming, will not start up again.

Press (S) the warning will disappear and sewing will be possible, the counter reduces continue. Press (S) again, the display will return to the initial value.

6. General Parameter Table (part)

6.1 Speed Parameter

| Range(rpm) | Description |
|------------|--|
| 500~5000 | Maximum speed |
| 150~500 | Minimum speed |
| 500~2500 | Speed of Start Backtack |
| 500~2500 | Speed of End Backtack |
| 500~2500 | Speed of Continuous Backtack |
| 500~5000 | Speed of Fixed Stitch |
| 150~300 | Speed of Thread Trimming |
| 200~500 | Speed of Slow Start |
| | 500~5000 150~500 500~2500 500~2500 500~2500 500~5000 150~300 |

6.2 Time Parameter

| SN | Range(ms) | Description | | | | |
|-----|-----------|--|--|--|--|--|
| T01 | 1~200 | Action time of the RVS SOL. | | | | |
| T02 | 1~200 | Release time of the RVS SOL | | | | |
| T03 | 1~200 | Timing before act the Wiper SOL. | | | | |
| T04 | 1~200 | Timing for act the Wiper SOL. | | | | |
| T05 | 1~500 | Timing before act the Foot Lifter SOL. | | | | |
| T06 | 1~500 | Timing before release Foot Lifter SOL. | | | | |
| T07 | 1~999 | Timing of act the Foot Lifter SOL with | | | | |
| 107 | | whole output. | | | | |
| T08 | 1~999 | Timing of act the RVS SOL with whole | | | | |
| 100 | | output. | | | | |
| T09 | 1~1000 | Timing of judge the Safety Switch. | | | | |
| T10 | 1- 200 | The pedal will be greater sensitive when | | | | |
| T10 | 1~200 | the value is smaller. | | | | |

6.3 Function Parameter

| SN | Range | Description | | | | |
|-----|-------|--|--|--|--|--|
| A01 | 0~1 | Needle Up/Down, see 5.3 | | | | |
| A02 | 0~1 | Fixed Stitches automatic sewing, see 5.2.2 | | | | |
| A03 | 0~1 | Needle Up/Down of Correct Stitches: | | | | |
| 703 | | 0 - random, 1 - A01 | | | | |
| A04 | 0~8 | Input1 function, see 5.9 | | | | |

| A05 | 0~8 | Inpet2 function, see 5.9 | | | | |
|-----|-----|--|--|--|--|--|
| A06 | 0~1 | Thread trimming | | | | |
| A08 | 0~1 | Wiper(must set A10 to "0") | | | | |
| A09 | 0~1 | Foot Lifter | | | | |
| A10 | 0~1 | Clamp | | | | |
| A11 | 0~1 | Counting the product quantity, see 5.12 | | | | |
| A12 | 0~1 | Lower thread counter, see 5.13 | | | | |
| A13 | 0~1 | After trimming, pullback to Needle Top. | | | | |
| A14 | 0~1 | The Foot Lifter will lift automatically when | | | | |
| A14 | 0~1 | stop, see 5.6 | | | | |
| A15 | 0~1 | The Foot Lifter will lift automatically after | | | | |
| AIS | | trimming, see 5.6 | | | | |
| | 0~1 | In Fix Stitches. If A02 was set to "1", the next | | | | |
| A16 | | segment will sew automatically after the Sta | | | | |
| | | Backtack. | | | | |
| | | In Fix Stitches. If A02 was set to "1", the End | | | | |
| A17 | 0~1 | Backtack and thread trimming will do | | | | |
| | | automatically after the last segment. | | | | |
| A18 | 0~1 | The machine will move to Needle Up and | | | | |
| A10 | | stop automatically as power on. | | | | |
| A19 | 0~2 | Function of pedal back -1: 0 - neutral | | | | |
| V19 | 0~2 | position, 1 – Foot Lifter, 2-thread trimming | | | | |
| A21 | 0~1 | Slow Start, see 5.4 | | | | |

6.4 Degree Parameter

| SN | Range | Description | | | |
|------|--------|--------------------------------------|--|--|--|
| SIV | Nanye | Description | | | |
| D01 | 0~359° | Needle Up degree. | | | |
| D02 | 0~359° | Needle Down degree. | | | |
| D03 | 0~359° | Trimmer act degree. | | | |
| D04` | 0~359° | Trimmer release degree. | | | |
| D05 | 0~359° | Reverse act degree. | | | |
| D06 | 0~359° | Reverse release degree. | | | |
| D07 | 0~359° | Clamp act degree. | | | |
| D08 | 0~359° | Clamp release degree. | | | |
| D09 | 0~359° | Reverse act degree(RVS.SW) | | | |
| D10 | 0~359° | Reverse release degree(RVS.SW) | | | |
| D11 | 0~359° | Reverse forbidden act degree(RVS.SW) | | | |
| D12 | 0~359° | Reverse allow act degree(RVS.SW) | | | |

6.5 Special function parameter

| O01 | SN | Range | Description | | | | |
|---|-----|-------|--|--|--|--|--|
| 5.4 O05 1~10 The duty of Foot Lifter SOL O06 0~1 The foot lifter SOL will be released automatically after the time desired(O07) O07 5~30s "The time desired" of O06 O09 1~10 The duty of RVS SOL O10 0~1 The RVS SOL will be released automatically after the time desired(O11) O11 5~30s "The time desired" of O10 | 001 | 4 40 | The number of stitches of slow start, see | | | | |
| O06 O~1 The foot lifter SOL will be released automatically after the time desired(O07) O07 5~30s "The time desired" of O06 O09 1~10 The duty of RVS SOL The RVS SOL will be released automatically after the time desired(O11) O11 5~30s "The time desired" of O10 | COT | 1~10 | 5.4 | | | | |
| 006 0~1 automatically after the time desired(007) 007 5~30s "The time desired" of 006 009 1~10 The duty of RVS SOL 010 0~1 The RVS SOL will be released automatically after the time desired(011) 011 5~30s "The time desired" of 010 | 005 | 1~10 | The duty of Foot Lifter SOL | | | | |
| automatically after the time desired(O07) 007 5~30s "The time desired" of O06 009 1~10 The duty of RVS SOL 010 0~1 The RVS SOL will be released automatically after the time desired(O11) 011 5~30s "The time desired" of O10 | 006 | 0.1 | The foot lifter SOL will be released | | | | |
| O09 1~10 The duty of RVS SOL. O10 0~1 The RVS SOL will be released automatically after the time desired(O11) O11 5~30s "The time desired" of O10 | 000 | 0~1 | automatically after the time desired(007) | | | | |
| O10 0~1 The RVS SOL will be released automatically after the time desired(O11) O11 5~30s "The time desired" of O10 | 007 | 5~30s | "The time desired" of O06 | | | | |
| O10 0~1 automatically after the time desired(O11) O11 5~30s "The time desired" of O10 | 009 | 1~10 | The duty of RVS SOL | | | | |
| automatically after the time desired(O11) O11 5~30s "The time desired" of O10 | 040 | 0~1 | The RVS SOL will be released | | | | |
| | 010 | | automatically after the time desired(O11) | | | | |
| 015 0-1 Encrypt the parameter interface, see 5.1. | 011 | 5~30s | "The time desired" of O10 | | | | |
| | 015 | 0-1 | Encrypt the parameter interface, see 5.1.4 | | | | |
| O17 0~1 Reset parameter to defaults, see 5.1.2 | 017 | 0~1 | Reset parameter to defaults, see 5.1.2 | | | | |

| 023 | 1~60s | The running time of aging test. | | | | | |
|------|---------------|--|--|--|--|--|--|
| 024 | 1~60s | The idle time of aging test. | | | | | |
| 025 | 1~720h | The total time of aging test. | | | | | |
| 026 | 0~2 | Set to "1/2" active the aging test. | | | | | |
| 027 | 0~9999 | Password, see 5.1.4 | | | | | |
| 031 | 0~1 | Safety switch | | | | | |
| 032 | 0~1 | Polarity of safety switch | | | | | |
| 042 | 0~1 | Foot Lifter when clamping. | | | | | |
| 048 | 1~10 | The duty of clamp SOL. | | | | | |
| O51 | 0~1 | Reset parameter to Factory Defaults, see 5.1.3 | | | | | |
| 053 | 1~10 | The duty1 of foot lifter SOL when clamping. | | | | | |
| 054 | 1~10 | The duty2 of foot lifter SOL when clamping. | | | | | |
| O55 | 1~10 | The duty3 of foot lifter SOL when clamping. | | | | | |
| O56 | 0~4095 | Pedal input MAX value: value ≥ O57 | | | | | |
| 057 | 0 4005 | Pedal input dividing value of high speed | | | | | |
| 057 | 0~4095 | and low speed: O56 ≥ value ≥ O58 | | | | | |
| 050 | 0.4005 | Pedal input dividing value of low speed | | | | | |
| O58 | 0~4095 | and Balance: O57 ≥ value ≥ O59 | | | | | |
| 050 | 0~4095 | Pedal input dividing value of Balance and | | | | | |
| O59 | | Foot lifter: O58 ≥ value ≥ O60 | | | | | |
| 060 | 0~4095 | Pedal input dividing value of Foot lifter and | | | | | |
| 000 | | Trimming: O59 ≥ value ≥ O61 | | | | | |
| 061 | 0~4095 | Pedal input MIN value: value ≤ O60 | | | | | |
| 062 | 0~250 | Pedal loop value | | | | | |
| | | Pedal mode: 0-linear;1-polyline;2- | | | | | |
| O63 | 0~5 | curve(slow → quick);3-curve(quick → | | | | | |
| 003 | | slow); 4-S curve(slow → quick → slow); | | | | | |
| | | 5-S curve(quick → slow → quick) | | | | | |
| 064 | 500~5000 | The speed of knee of polyline | | | | | |
| O65 | 0~4095 | The value of knee of polyline: O56 ≥ value ≥ | | | | | |
| | | O57 | | | | | |
| O66 | 1~10 | The period of Foot Lifter SOL(ms) | | | | | |
| 067 | 1~10 | The period of RVS SOL(ms) | | | | | |
| | | Mode of the End Backtack: 0- Stop first, | | | | | |
| 068 | 0~1 | then act RVS SOL; 1-Act RVS SOL when | | | | | |
| | | running | | | | | |
| O69 | 0~1 | Mode of correct stitches: 0-before trimming | | | | | |
| | | only; 1-only if stop | | | | | |
| 072 | 0~10 | Add torque when low speed | | | | | |
| 7. S | ional Checkin | a | | | | | |

7. Signal Checking

Press for 1 second or more when power on, display "TEST". Press to increase SN, press p to decrease SN.

7.1 Pedal: 2 modes, press A+ select

- (1) Display the value of pedal;
- (2) Display the different pedal position as below:

| Display | Meanings | Descriptions |
|---------|-------------|----------------------------|
| HS02~99 | High speed | The second segment forward |
| LS01 | Low speed | The first segment forward |
| BL | Balance | Default |
| FP | Foot lifter | The first segment backward |

| TM | Trimming | The second segment of backward |
|------|----------|--------------------------------|
| ERRO | Fault | Pedal fault or disconnected |

7.2 Synchronizer: Turn the hand wheel by hand equably, display "UP 1" or "UP".

7.3 Switch: B - Input1; C - Input2; D - Safety Switch

7.4 Encoder signal of motor: Turn the hand wheel by hand equably, display the encode count of motor, the error is ±5 normally

7.5 Solenoid: display "TRWF", press act solenoid. T - trimmer, R - RVS, W -- wiper(or clamp), F - Foot Lifter

7.6 Version of software: v100, e.g. the version is v 1.00

7.7 Date of software: A displays year, D-2013, E-2014, and so on. B displays month, A-October, B-November, C-December. CD

display day. E.g.: "D815" - 2013.8.15

7.8 AC power

7.9 BUS power

7.10 Phase A current, Range is 2050±50

7.11Phase B current, Range is 2050±50

8. Setup zero point

Press of for 1 second or more when power on, display "ZERO". Turn hand wheel equably, display the current degree.

Turn hand wheel to top dead center, then press and display "SET" to set zero degree point.

9. Measurement of Error and Warning

| code | Causation | Measurement | | |
|------|---------------------|------------------------------|--|--|
| E 01 | Voltage is too high | Check the AC power. | | |
| E 03 | Voltage is too high | Check the AC power. | | |
| E 06 | Current is overload | Check the load. | | |
| E 08 | Load is too heavy | Check the load. | | |
| E 09 | Motor error | Check motor wire | | |
| E 10 | Synchronizer error | Check synchronizer, see 7.2. | | |
| PEDL | Pedal warning | Release the pedal. | | |
| CARE | Safety SW warning | Check Safety SW., see 5.10. | | |
| KEY1 | Input1 warning | Check Input1 | | |
| KEY2 | Input2 warning | Check Input1 | | |

Appendix: 7-segment Display Characters Compare Table

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|----------|-----------|---|------------|--|---|-----------------|---|---|
| | 1 | Z | | H | COLUMN TO SERVICE SERV | 5 | 7 | 8 | 9 |
| Α | В | С | D | E | F | G | Н | ı | J |
| F | | (<u></u> | | | F | | 1-1 | 1 | L |
| К | Ļ, | M | N | 0 | р | Q | R | S | Т |
| L | | | | <u>C</u> i | | q | l ^{am} | | |
| Ü | V | W | Х | Y | Z | | | | |
| U | L | | | | 4000 4000 4000 | | | | |